



Segmentation with CNNs

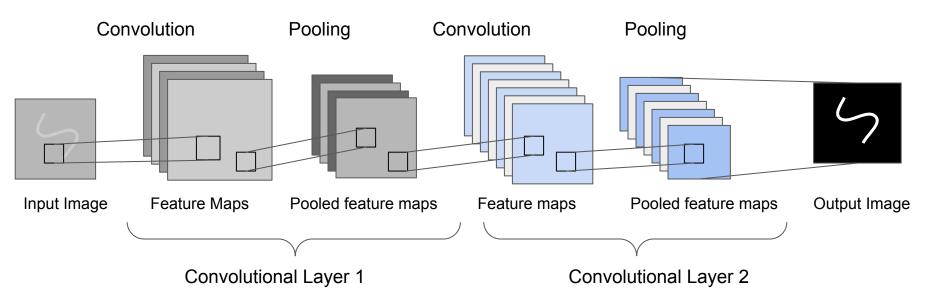
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14/03/2022

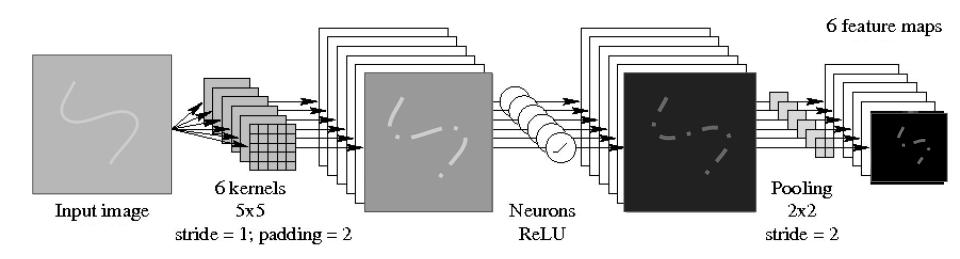
Intro

- 1. CNN
- 2. UNet
- 3. ResNet
- 4. Attention ResNet
- 5. Data preparation
- 6. Results

Convolutional Neural Networks (CNN)



Convolutional Layer 1



128 **UNet** Output Images Input Images f(x) Outputs Conv. + ReLU Conv. + ReLU 512 Inputs Skip-connection 2x (3x3 DSC, BN, ReLu) CBAM 512 Max Pool 2x2

256

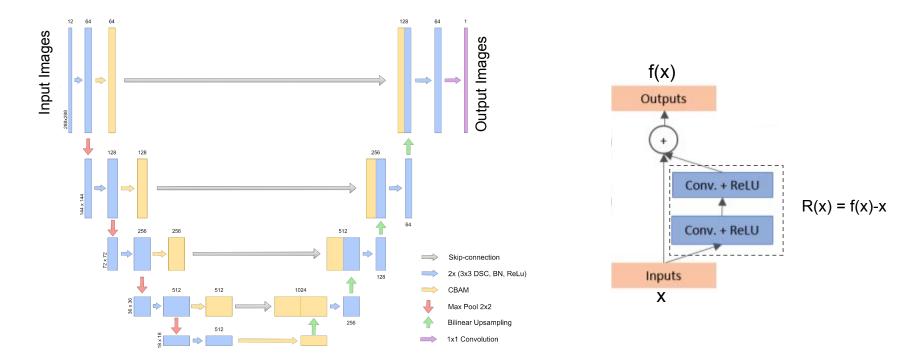
Layers are trying to learn f(x) for the given input x.

Recurrent Residual Convolutional Neural Network based on U-Net (R2U-Net) for Medical Image Segmentation https://arxiv.org/pdf/1802.06955.pdf

Bilinear Upsampling

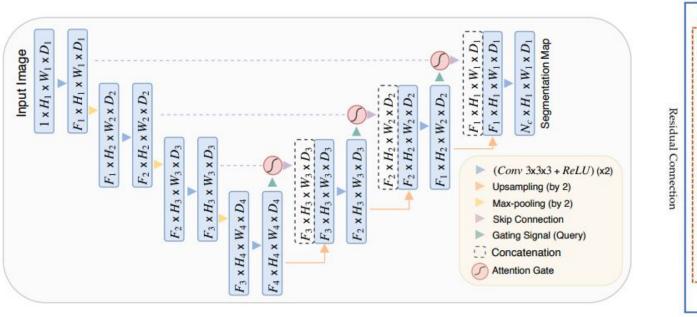
1x1 Convolution

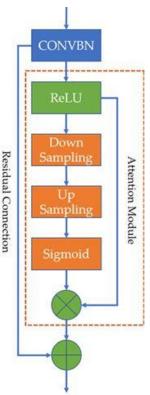
ResNet



Here, Layers are trying to learn the residual unlike UNet where they try to learn f(x). ResNet helps in solving the problem of vanishing gradients and also of overfitting to an extent.

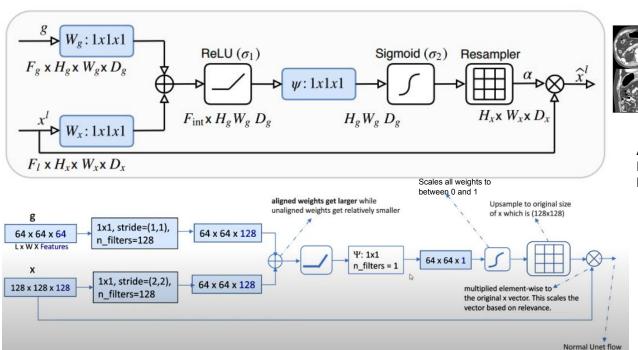
Attention ResNet

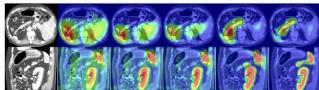




Architecture is very similar to ResNet, except there is an extra block called attention block. Attention in U-Nets is a method to highlight only the relevant activations during the training.

Attention Block

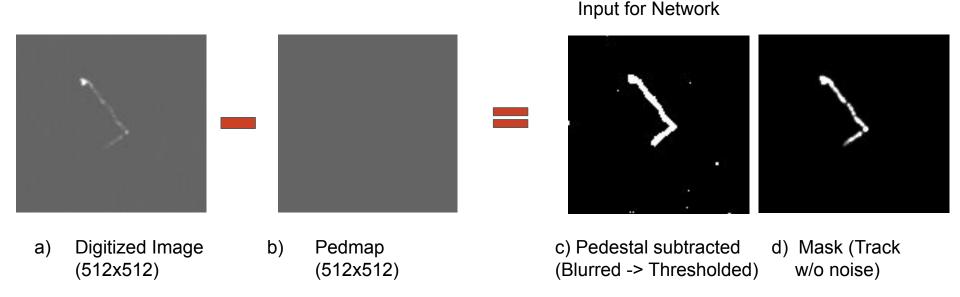




Attention U-Net: Learning Where to Look for the Pancreas https://arxiv.org/pdf/1804.03999.pdf

It reduces computation resources wasted on irrelevant activations and provides better generalization of the network.

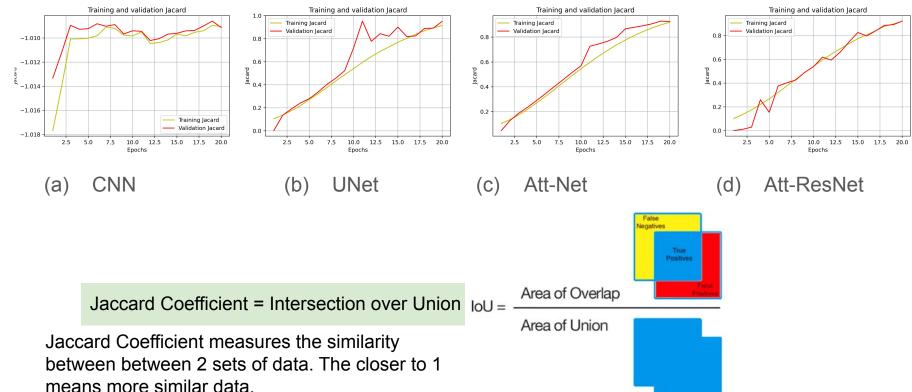
Data Preparation



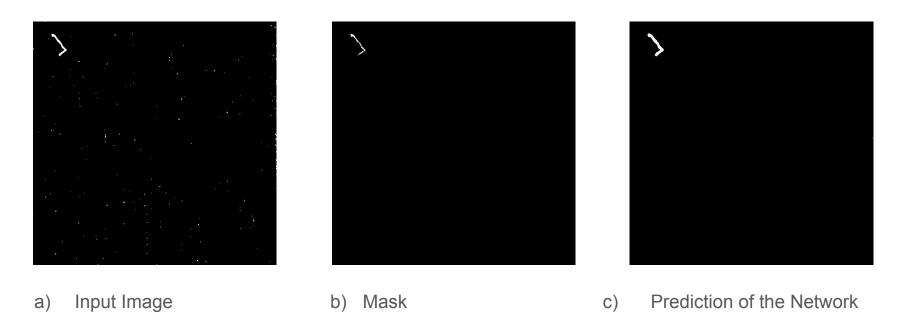
Pedestal map is subtracted from the digitized image. Pedestal subtracted image is then passed through a median filter with a kernel size of 3. Blurred image is thresholded with a threshold of 1 (pixels with intensity more than 1 becomes 255 and rest 0). These images are input for the network.

Masks are produced by digitizing the tracks without noise. Network is trained to produce images similar to masks.

Training and Validation accuracy



Prediction from the Network



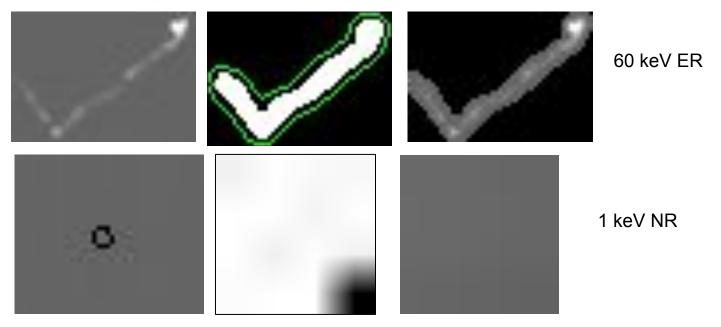
Example shown here is for a 60 keV ER.

Prediction from the Network



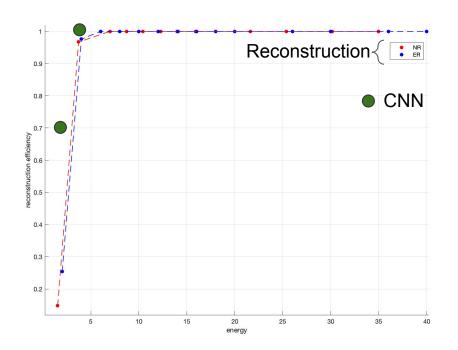
Example shown here is for a 1 keV NR.

Instance Segmentation



Clusters are found using OpenCV module.

Reconstruction Efficiency



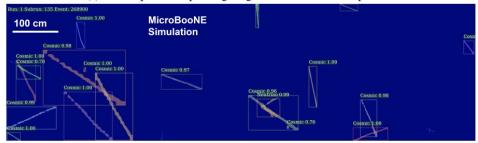
Only 100 events of each energy were used to check the efficiency of CNN.

Reconstruction efficiency at 1 keV of NR is around 70% and at 3 keV NR is 100%.

Plan:







(b) A simulated neutrino interaction overlaid on cosmic ray muons from data, labeled by sMask-RCNN

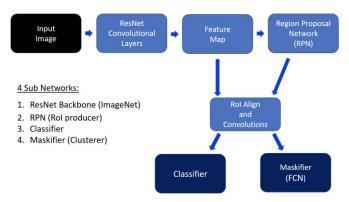


Figure 3: Network Architecture for Mask-RCNN in MicroBooNE.

Cosmic ray muon clustering for the MicroBooNE liquid argon time projection chamber using sMask-RCNN https://arxiv.org/pdf/2201.05705.pdf